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6123329081

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Sheet 1 of 1

<b>FORM 1449*</b> <b>INFORMATION DISCLOSURE STATEMENT</b> <b>IN AN APPLICATION</b> <small>(Use several sheets if necessary)</small>		Docket Number: 12100.7USCI	Application Number: 10/712,802
		Applicant: LI ET AL	
		Filing Date: November 13, 2003	Group Art Unit: 2877

U.S. PATENT DOCUMENTS						
EXAMINER INITIAL	DOCUMENT NO.	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATE
MS	4,997,369	03/05/1991	Shafir			
	5,017,139	05/21/1991	Mushabac			
	5,050,608	09/24/1991	Watanabe et al.			
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	5,824,007	10/20/1998	Faraz et al.			
	5,847,528	12/08/1998	Hui et al.			
	5,891,034	04/06/1999	Buchholz			
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OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, Etc.)		
MS		Cosselin et al. "On the Development of the Agile Eye," <i>IEEE Robotics &amp; Automation Magazine</i> , pp. 39-37 (December 1996).
		Ham et al. "Spherical Four-Bar Linkage Mechanism for Continuous Passive Movement Rehabilitation Treatment of the Ankle," <i>Proceedings of The 1996 ASME Design Engineering Technical Conferences and Computers in Engineering Conference</i> , pp. 1-6 (August 18-22, 1996).
		Hong et al. "Design of Adjustable Spherical Four-Bar Linkages as Continuous Passive Motion Devices for Anatomic Joints Rehabilitation," <i>Proceedings of The 1996 ASME Design Engineering Technical Conferences and Computers in Engineering Conference</i> , pp. 1-10 (August 18-22, 1996).
		Merlet, R. New Positional Device, "A New Family of Six Degrees of Freedom Positional Devices," <a href="http://www.cyber.com/hanouch/6dof.html">http://www.cyber.com/hanouch/6dof.html</a> , pp. 1-12 (Printed September 14, 2001).
		Merlet, "Parallel manipulators: state of the art and perspectives," <a href="http://www-sop.inria.fr/saga/personnel/merlet/Etaux_etape_de_lart.html">http://www-sop.inria.fr/saga/personnel/merlet/Etaux_etape_de_lart.html</a> , pp. 1-9 (Printed May 18, 1999).
		"Kinematics and dynamics of parallel mechanisms and manipulators", <a href="http://www.robots.gme.ulaval.ca/">http://www.robots.gme.ulaval.ca/</a> , pp. 1-10 (Printed May 18, 1999).
MS		December 1996 Robotics and Automation Index and Abstracts, <a href="http://www.ncsu.edu/IEEE-RAS/RAM/RAMIssues/RAMIssues/RAMv103n004.html">http://www.ncsu.edu/IEEE-RAS/RAM/RAMIssues/RAMIssues/RAMv103n004.html</a> , pp. 1-3 (Printed May 18, 1999).

EXAMINER	/Michael Stafira/	DATE CONSIDERED	08/15/2006
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EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw line through citation if not in conformance and not considered. Include copy of this form for next communication to the Applicant.

\*Substitute Disclosure Statement Form (PTO-1449)

Patent and Trademark Office; U.S. DEPARTMENT OF COMMERCE

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